

FIG. 2

✓ 350

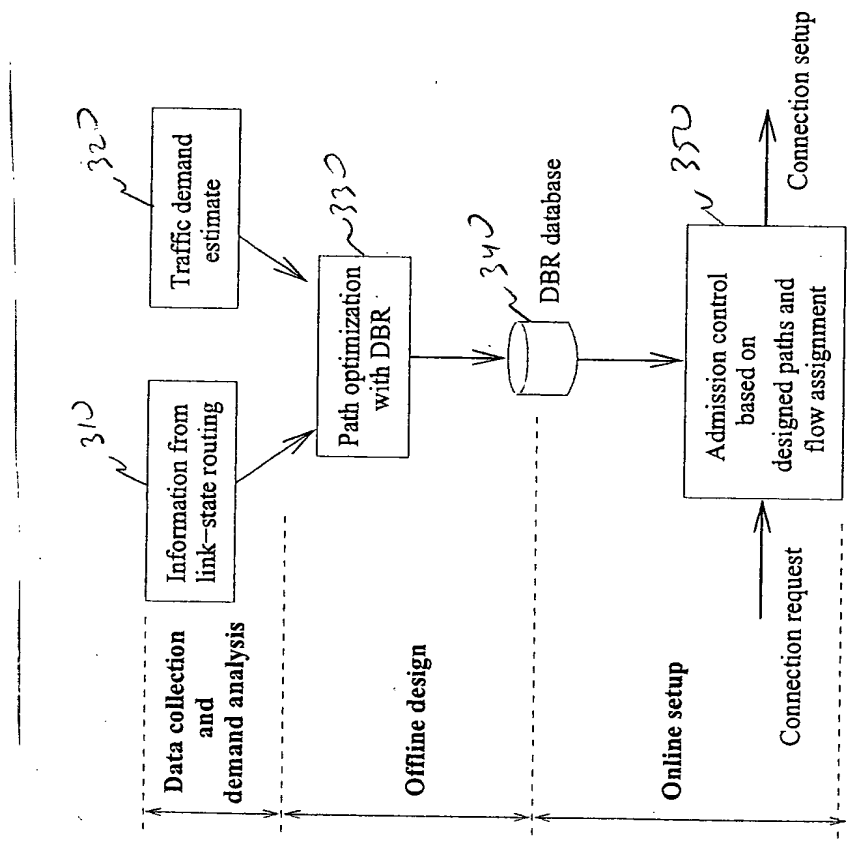


FIG. 3

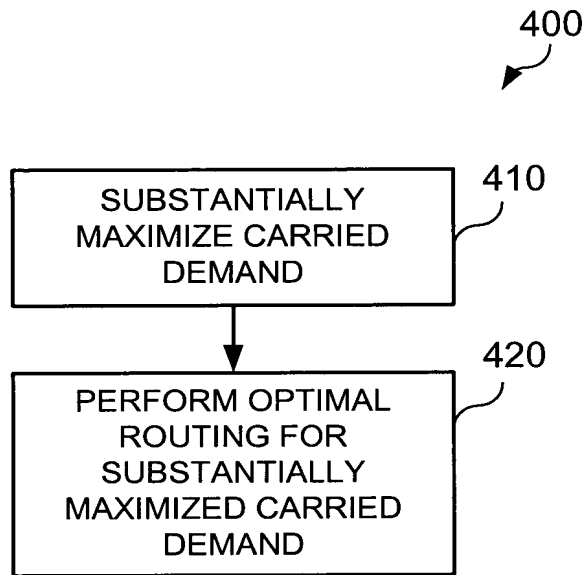


FIG. 4

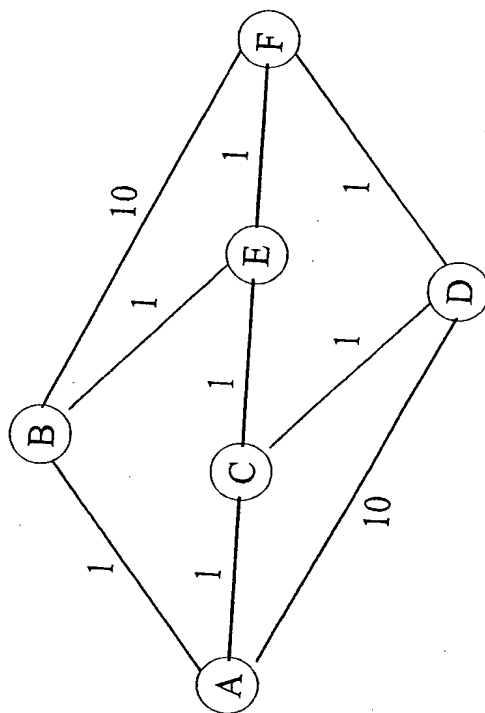


FIG. 5

```

Adaptive DBR:
if  $v_{sd} - \hat{v}_{sd}(t) > 0$ 
    prune with  $TR=0$ 
    if a DBR path exists
        setup the DBR connection
    else
        prune with  $TR=r$ 
        compute shortest path on the pruned network
        setup the connection if possible
else
    prune with  $TR=r$ 
    if a DBR path exists
        setup the DBR connection
    else
        prune with  $TR=r$ 
        compute shortest path on the pruned network
        setup the connection if possible

```

FIG. 6

} 2

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CSPF_TR:
prune with TR=0
compute shortest path on the pruned network
if the resulting path length =  $l_{min}(s, d)$ 
    setup the connection
else
    prune with TR=r
    compute shortest path on the pruned network
    setup the the connection if possible
  
```

F16.7